

EN.540.635 Software Carpentry

Lecture 10 Searching Algorithms and Gradient-Based Minimization in Optimization Problems

Searching

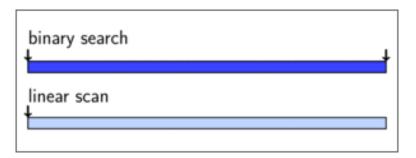


Finding the index of a value/object in a list:

- In a list, where is the maximum?
- In a list, where is the minimum?
- In a list, where is a specific value located?

Two main ideas:

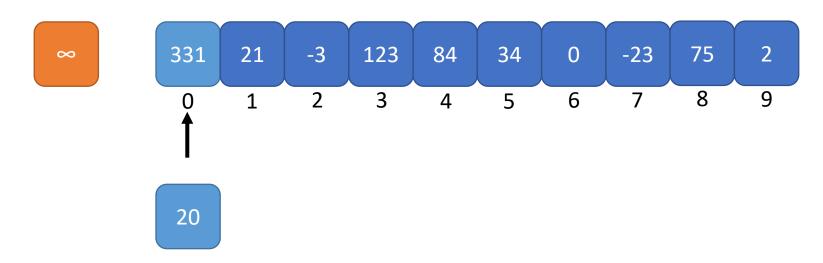
- Linear searching
- o Binary searching





Let's find the smallest number larger than 20 in this list

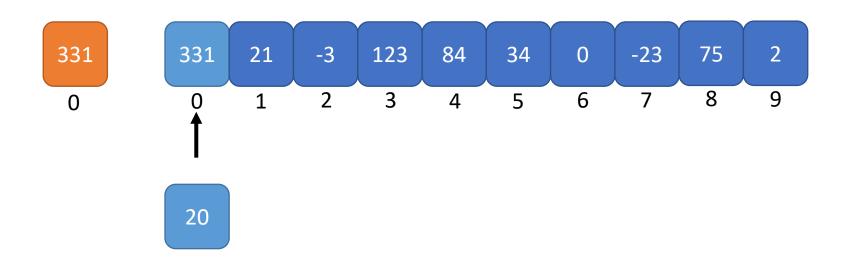
- \circ Check if N > 20
- \circ Check if N < N_{prev}





Let's find the smallest number larger than 20 in this list

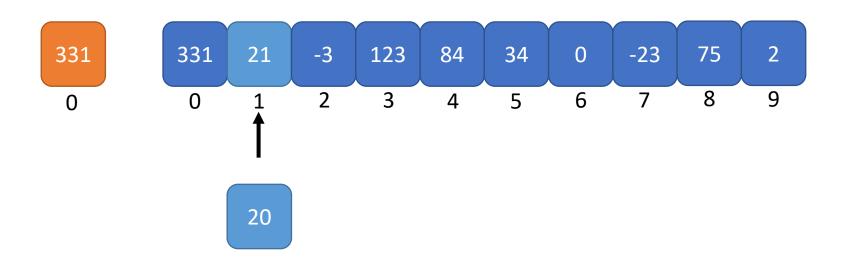
○ Check if N > 20○ Check if N < N_{prev}yes





Let's find the smallest number larger than 20 in this list

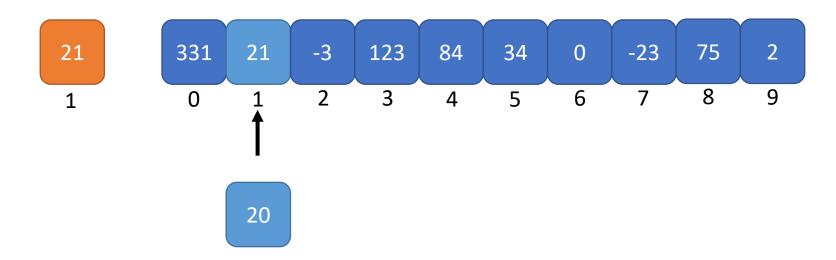
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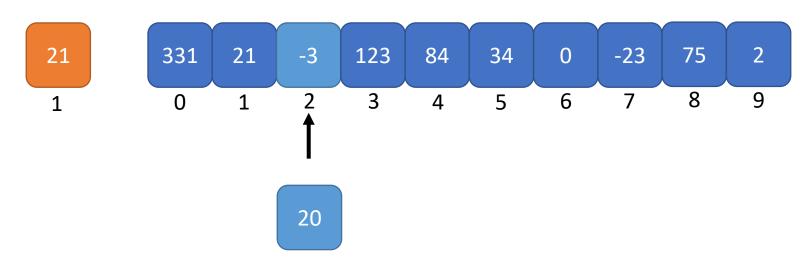
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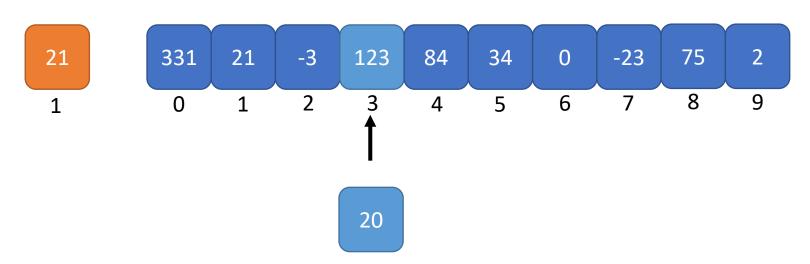


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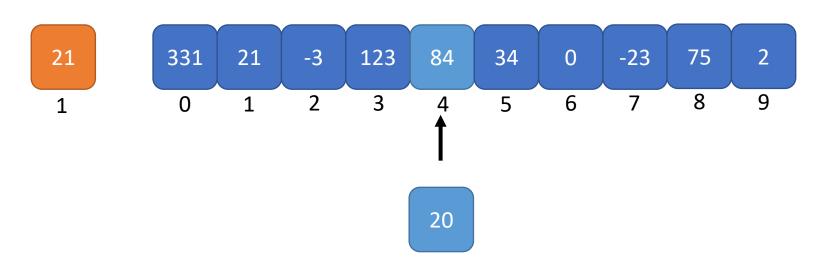


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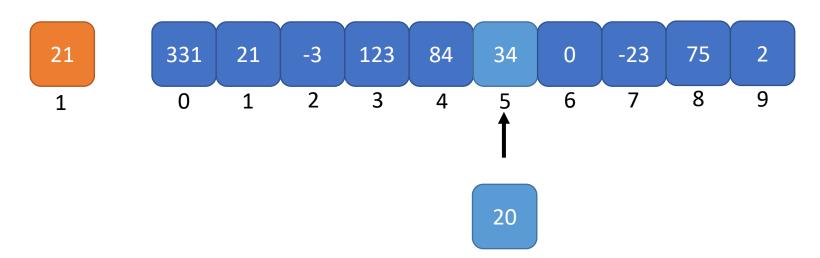




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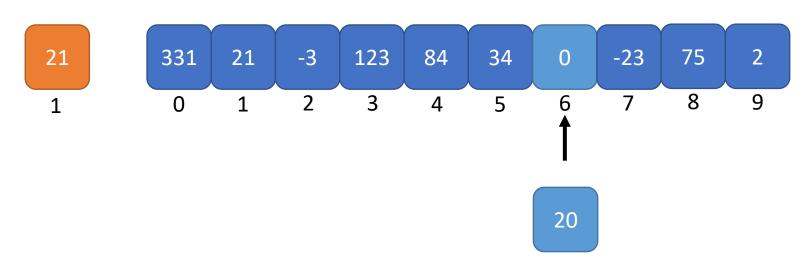
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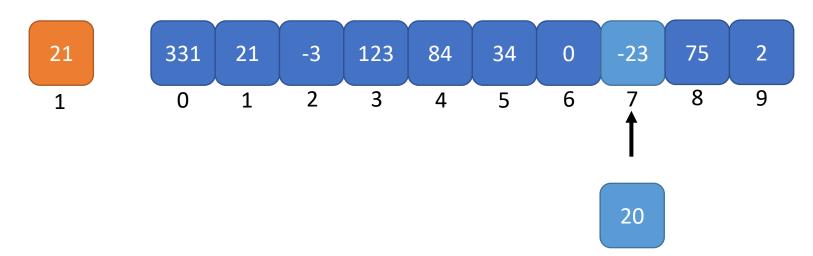
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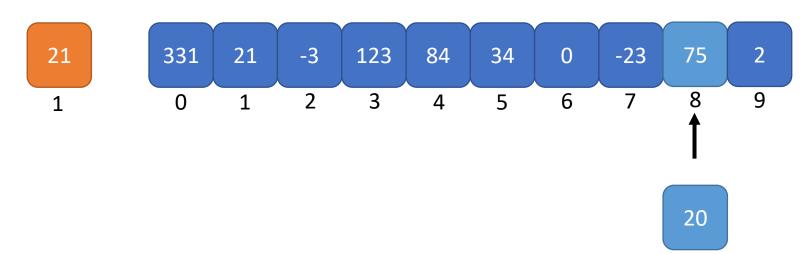


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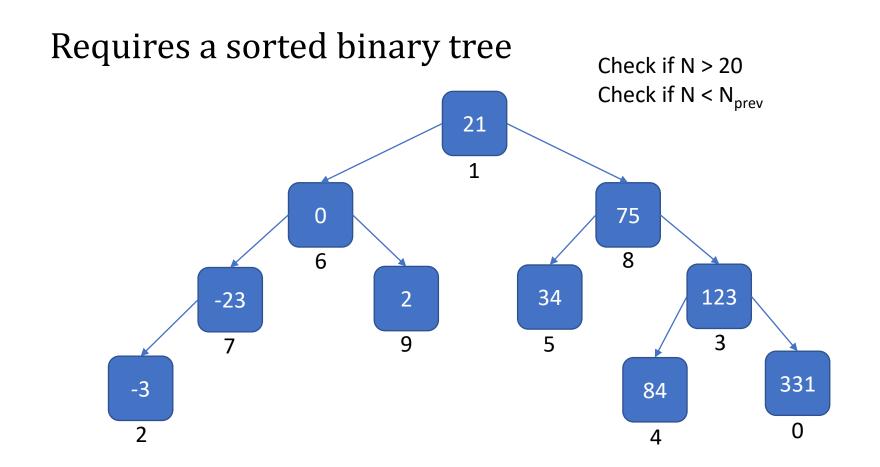




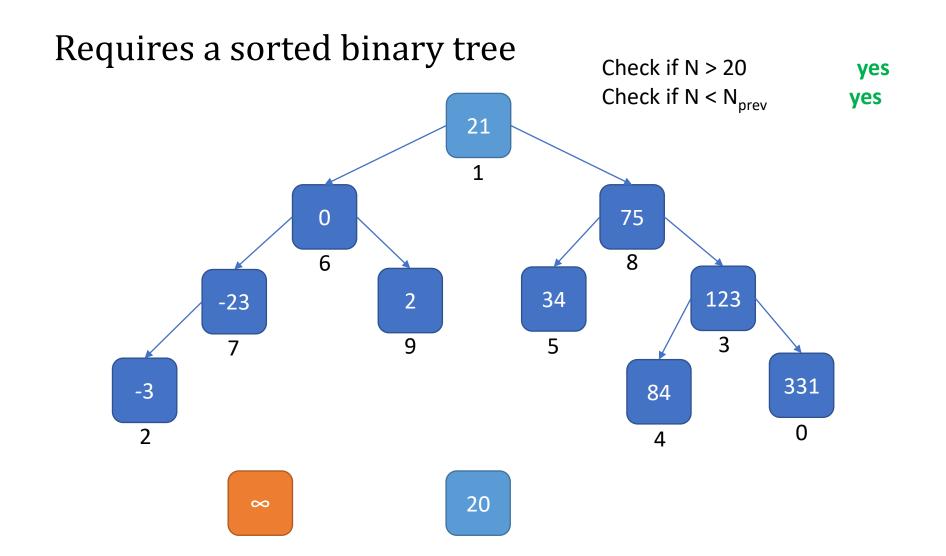
Requires a sorted binary tree



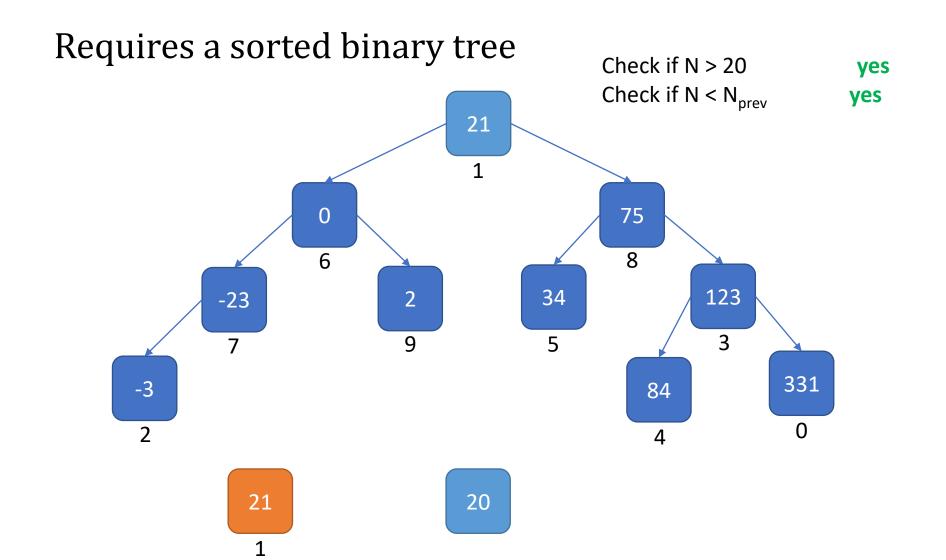




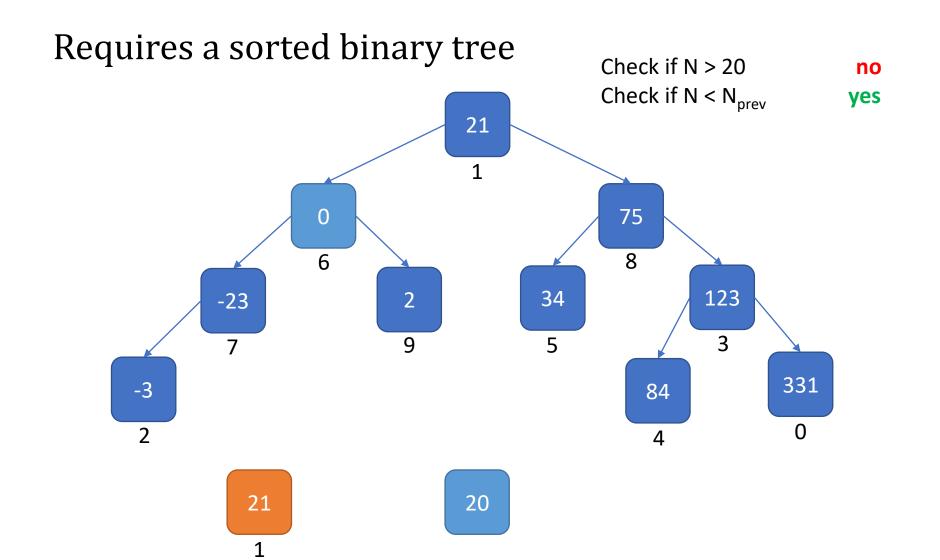




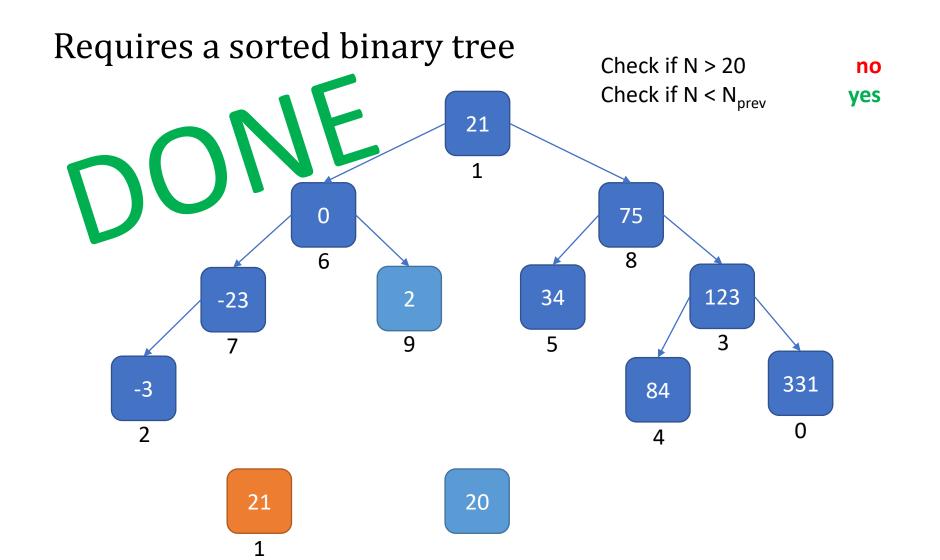












Comparing Linear and Binary Search



• Linear search took 20 comparisons to find the smallest number larger than 20, while the binary search only took 6!

Should we only ever use binary?

• What situations is linear better in?

Practice



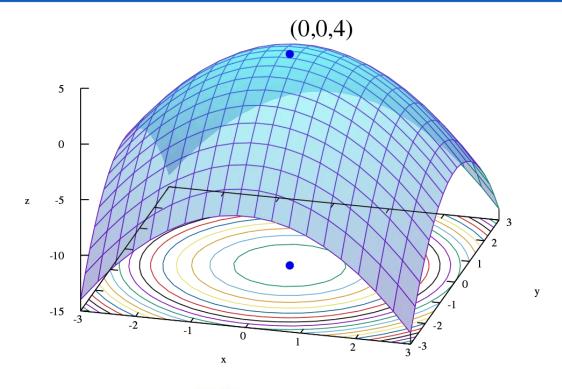
• We can write our own linear and binary searching algorithms in Python.

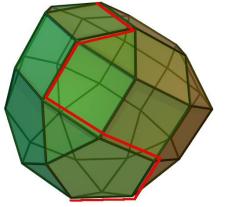
- There are several other searching algorithms besides linear and binary search:
 - Jump search
 - Interpolation search
 - Exponential search
 - Recursive searching methods

Optimization



- Optimization allows us to find the best values for a given set of mathematical constraints.
- A common example is curve fitting.
- Useful in computational research, as well as data analysis for experimental work.
- In Python, there are optimization functions that are typically bundled together in software packages.

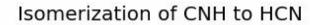


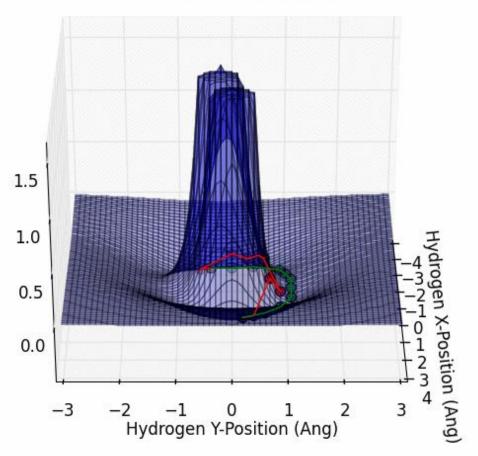


Optimization Examples

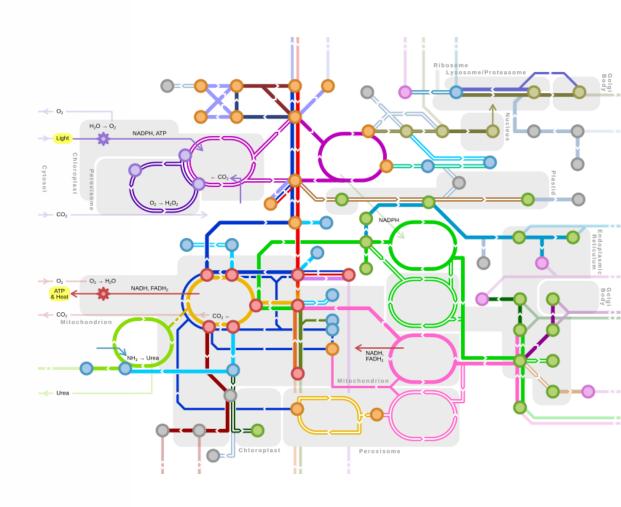


Nudged elastic band (NEB):





Optimizing Reaction Fluxes in a Metabolic Network:



Optimization Techniques and Algorithms



- In this class, we'll be focusing on some iterative methods that make use of Hessians and gradients.
- Some examples include:
 - Newton's method
 - Quasi-Newton methods
 - Conjugate gradient
 - Gradient descent/steepest descent

General Formulation for Gradient-based Problems



- We have a function f(x), and we want to find a value x such that f(x) is minimized.
- Typically, f(x) is (twice) differentiable, convex, and exists within the Euclidean space \mathbb{R}^n , where n is the dimension. There may also be a set of constraints that we have to adhere to.

• In an iterative optimization method, we guess an initial value x_0 and the update our value using the gradient in some way until we converge at the minimum:

$$x_{k+1} = x_k + s_k \nabla f(x_k)$$

Example of a Quasi-Newton Method



- 1. Choose a starting point, x_0
- 2. Calculate the search by approximating the inverse Hessian, H⁻¹
- 3. Calculate the change in x by the following expression:

$$X_{k+1} = X_k - [H^{-1}]_k \nabla f(X_k)$$

- 4. Determine x_{k+1} from the expression above.
- 5. Check if the method has converged we see if the gradient is equal to 0.
- 6. Repeat from step 2 until we have converged.

Other Gradient-Based Methods



• There are other methods where there are different ways to approximate the inverse Hessian (or not use it at all).

Gradient descent/steepest descent:

$$\mathbf{x}_{n+1} = \mathbf{x}_n - \gamma_n
abla F(\mathbf{x}_n), \ n \geq 0.$$

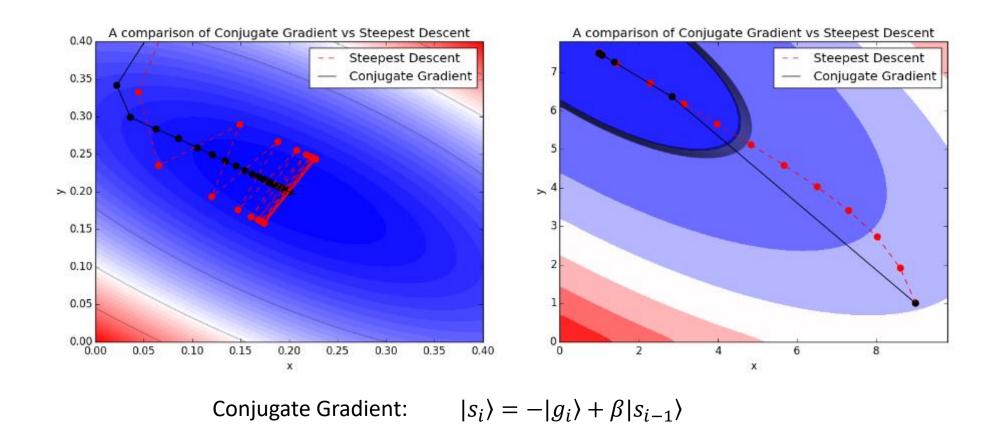
• Broyden-Fletcher-Goldfarb-Shanno (BFGS):

$$H_{k+1} = H_k + \frac{yy^T}{y^Ts} - \frac{H_k ss^T H_k}{s^T H_k s}$$

$$s = x_{k+1} - x_k$$
, $y = \nabla f(x_{k+1}) - \nabla f(x_k)$

Conjugate Gradient





Fletcher-Reeves Method

SciPy's Optimize Function



• SciPy has an optimize function that has many different solving algorithms built in.

scipy.optimize.minimize(fun, x0, args=(), method=None, jac=None, hess=None, hessp=None, bounds=None, constraints=(), tol=None, callback=None, options=None)

[source]

Minimization of scalar function of one or more variables.

Parameters:

fun : callable

The objective function to be minimized.

where x is an 1-D array with shape (n,) and *args* is a tuple of the fixed parameters needed to completely specify the function.

x0 : *ndarray*, *shape* (*n*,)

Initial guess. Array of real elements of size (n,), where 'n' is the number of independent variables.